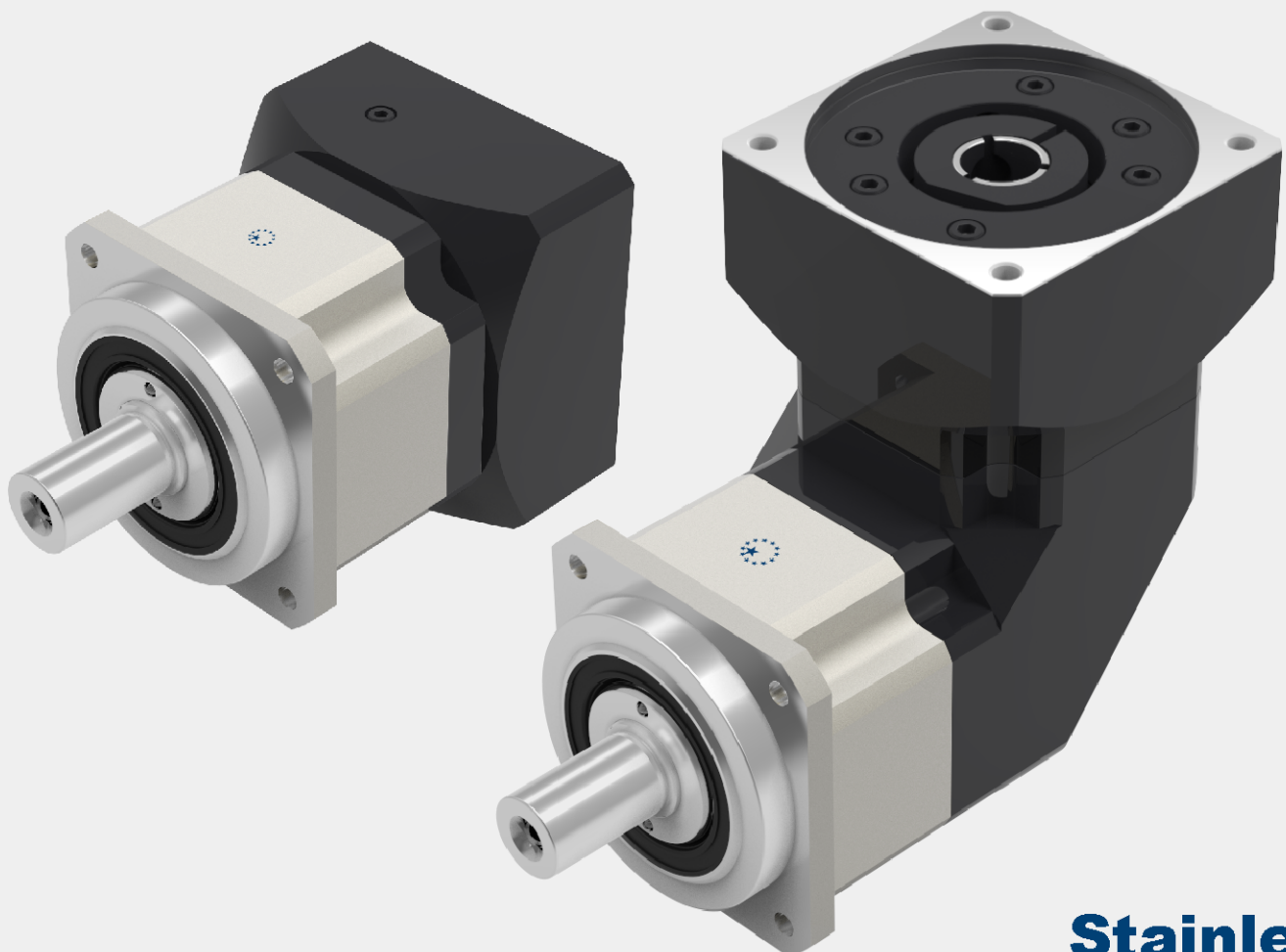




APEX DYNAMICS, INC.

**HIGH PRECISION
PLANETARY GEARBOX**

AB / ABR Series



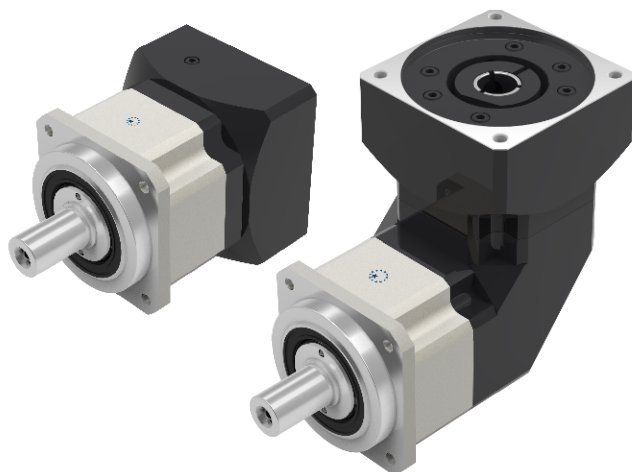
Stainless

**APEX DYNAMICS, INC.**

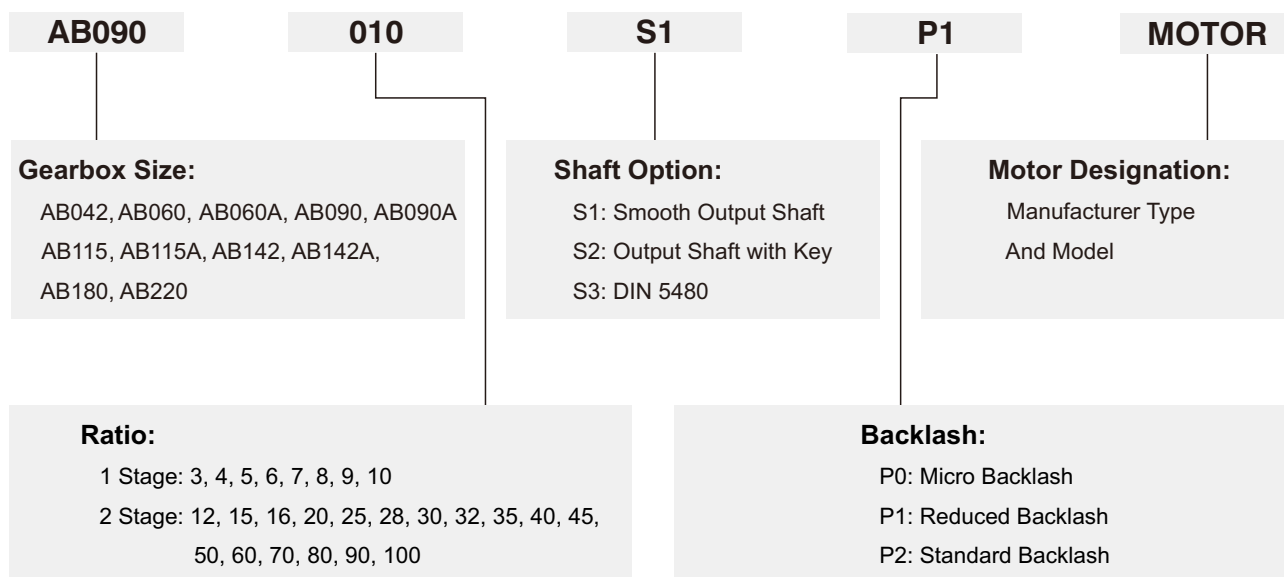
Apex Dynamics, Inc. is the world's most productive manufacturer of servomotor drive planetary gearboxes for precision automation machinery. From our 800,000+ square foot ISO 9001:2008 manufacturing facility, based in Taichung, Taiwan, we manufacture to stock using the newest precision machine tools and quality test and inspection equipment. Complete focus on quality and precision allows us to produce our high quality gearheads at precision levels down to less than 1 arc minute (1/60 th of a degree), with consistency and high reliability.

Based on more than twenty years of accumulated manufacturing and marketing experience, plus the highest level of technical production capabilities, Apex Dynamics, Inc. designs and builds technically advanced, high speed, low backlash servo application planetary gearboxes. Our Break through patented technology (over 6 patents), provides the customer with the optimum high precision helical reducer at a reasonable price. We are continuously improving processes, finding proper and effective methods to provide customers new solutions for difficult applications, and developing new products.

The primary focus in daily operation is quality. We pride ourselves on our dedication to quality; our duty - is customer satisfaction.

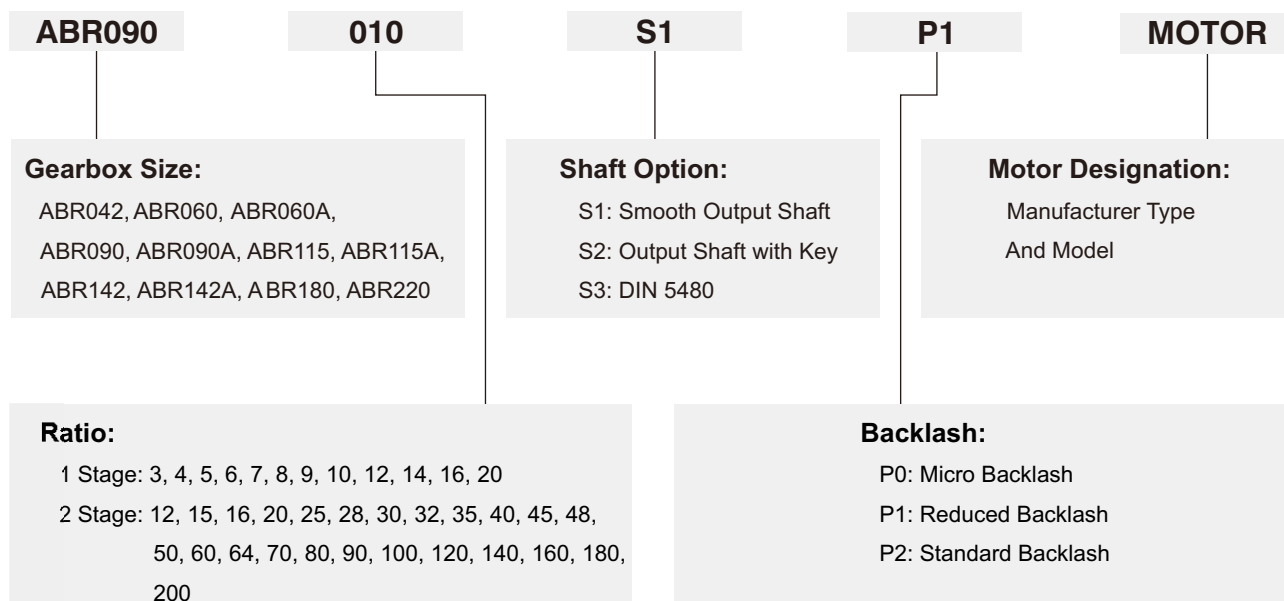


AB Series



Ordering Example: AB090-010-S1-P1 / SIEMENS 1FT6 041-4AF71

ABR Series



Ordering Example: ABR090-010-S1-P1 / SIEMENS 1FT6 041-4AF71

Specifications / AB Series

Gearbox Performance

Model No.		Stage	Ratio ^A	AB042	AB060	AB060A	AB090	AB090A	AB115	AB115A	AB142	AB142A	AB180	AB220
Nominal Output Torque T_{2N}	Nm	1	3	20	55	—	130	—	208	—	342	—	588	1,140
			4	19	50	—	140	—	290	—	542	—	1,050	1,700
			5	22	60	—	160	—	330	—	650	—	1,200	2,000
			6	20	55	—	150	—	310	—	600	—	1,100	1,900
			7	19	50	—	140	—	300	—	550	—	1,100	1,800
			8	17	45	—	120	—	260	—	500	—	1,000	1,600
			9	14	40	—	100	—	230	—	450	—	900	1,500
			10	14	40	—	100	—	230	—	450	—	900	1,500
		2	12	19	50	50	140	140	290	290	542	542	1,050	1,700
			15	20	55	55	130	130	208	208	342	342	588	1,140
			16	19	50	50	140	140	290	290	542	542	1,050	1,700
			20	19	50	50	140	140	290	290	542	542	1,050	1,700
			25	22	60	60	160	160	330	330	650	650	1,200	2,000
			28	19	50	50	140	140	300	300	550	550	1,100	1,800
			30	20	55	55	150	150	310	310	600	600	1,100	1,900
			32	17	45	45	120	120	260	260	500	500	1,000	1,600
			35	19	50	50	140	140	300	300	550	550	1,100	1,800
			40	17	45	45	120	120	260	260	500	500	1,000	1,600
			45	14	40	40	100	100	230	230	450	450	900	1,500
			50	22	60	60	160	160	330	330	650	650	1,200	2,000
			60	20	55	55	150	150	310	310	600	600	1,100	1,900
			70	19	50	50	140	140	300	300	550	550	1,100	1,800
			80	17	45	45	120	120	260	260	500	500	1,000	1,600
			90	14	40	40	100	100	230	230	450	450	900	1,500
			100	14	40	40	100	100	230	230	450	450	900	1,500
Emergency Stop Torque T_{2NOT}^B	Nm	1,2	3 times of Nominal Output Torque											
Nominal Input Speed n_{1N}	rpm	1,2	3~100	5,000	5,000	5,000	4,000	4,000	4,000	4,000	3,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~100	10,000	10,000	10,000	8,000	8,000	8,000	8,000	6,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~10	—	—	—	≤1	—	≤1	—	≤1	—	≤1	≤1
		2	12~100	—	—	—	—	—	≤3	≤3	≤3	≤3	≤3	≤3
Reduced Backlash P1	arcmin	1	3~10	≤3	≤3	—	≤3	—	≤3	—	≤3	—	≤3	≤3
		2	12~100	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5	≤5
Standard Backlash P2	arcmin	1	3~10	≤5	≤5	—	≤5	—	≤5	—	≤5	—	≤5	≤5
		2	12~100	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Torsional Rigidity	Nm/arcmin	1,2	3~100	3	7	7	14	14	25	25	50	50	145	225
Max. Radial Load F_{2r}^C	N	1,2	3~100	780	1,530	1,530	3,250	3,250	6,700	6,700	9,400	9,400	14,500	50,000
Max. Axial Load F_{2aB}^C	N	1,2	3~100	390	765	765	1,625	1,625	3,350	3,350	4,700	4,700	7,250	25,000
Service Life ^D	hr	1,2	3~100	20,000										
Efficiency η	%	1	3~10	≥97%										
		2	12~100	≥94%										
Weight	kg	1	3~10	0.6	1.3	—	3.7	—	7.8	—	14.5	—	29	48
		2	12~100	0.8	1.5	1.9	4.1	5.3	9	11.4	17.5	20.7	33	60
Operating Temp	°C	1,2	3~100	-10°C~90°C										
Lubrication		1,2	3~100	Synthetic lubrication oils										
Degree of Gearbox Protection		1,2	3~100	IP65										
Mounting Position		1,2	3~100	all directions										
Noise ($n_1=3000$ rpm, $i=10$, No load) ^E	dB(A)	1,2	3~100	≤56	≤58	≤60	≤60	≤63	≤63	≤65	≤65	≤67	≤67	≤70

A. Ratio ($i=N_n/N_{out}$)B. Max. acceleration torque T_{2B} = 60% of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

D. For continuous operation, the service life time is less than 10,000 hrs

E. These values are measured by gearbox with ratio = 10 (1-stage) or ratio = 100 (2-stage) at 3,000 rpm no loading.

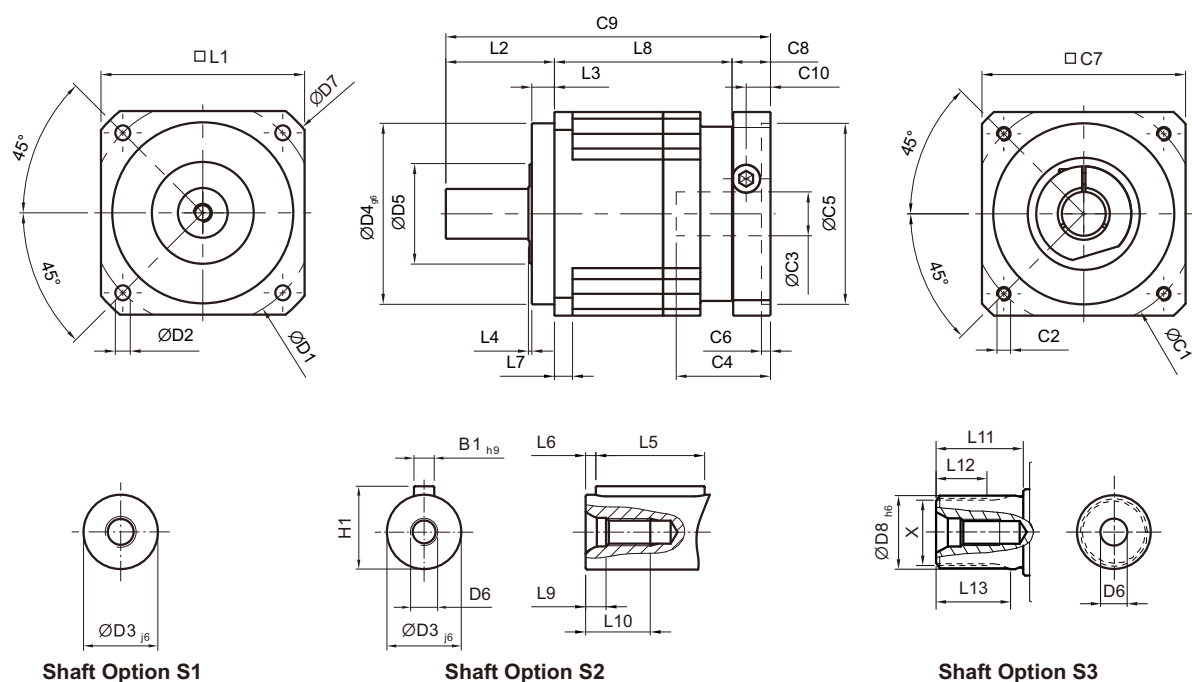
By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher

Ordering Code

Gearbox Inertia

Model No.		Stage	Ratio	AB042	AB060	AB060A	AB090	AB090A	AB115	AB115A	AB142	AB142A	AB180	AB220
Mass Moments of Inertia J_1	kg • cm ²	1	3	0.03	0.16	—	0.61	—	3.25	—	9.21	—	28.98	69.61
			4	0.03	0.14	—	0.48	—	2.74	—	7.54	—	23.67	54.37
			5	0.03	0.13	—	0.47	—	2.71	—	7.42	—	23.29	53.27
			6	0.03	0.13	—	0.45	—	2.65	—	7.25	—	22.75	51.72
			7	0.03	0.13	—	0.45	—	2.62	—	7.14	—	22.48	50.97
			8	0.03	0.13	—	0.44	—	2.58	—	7.07	—	22.59	50.84
			9	0.03	0.13	—	0.44	—	2.57	—	7.04	—	22.53	50.63
			10	0.03	0.13	—	0.44	—	2.57	—	7.03	—	22.51	50.56
		2	12	0.03	0.03	0.16	0.16	0.61	0.61	3.25	3.25	9.21	9.21	28.98
			15	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			16	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67
			20	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			25	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			28	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67
			30	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			32	0.03	0.03	0.14	0.14	0.48	0.48	2.74	2.74	7.54	7.54	23.67
			35	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			40	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			45	0.03	0.03	0.13	0.13	0.47	0.47	2.71	2.71	7.42	7.42	23.29
			50	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
			60	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
			70	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
			80	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
			90	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51
			100	0.03	0.03	0.13	0.13	0.44	0.44	2.57	2.57	7.03	7.03	22.51

Dimensions (1-stage, Ratio $i=3\sim 10$) / AB Series



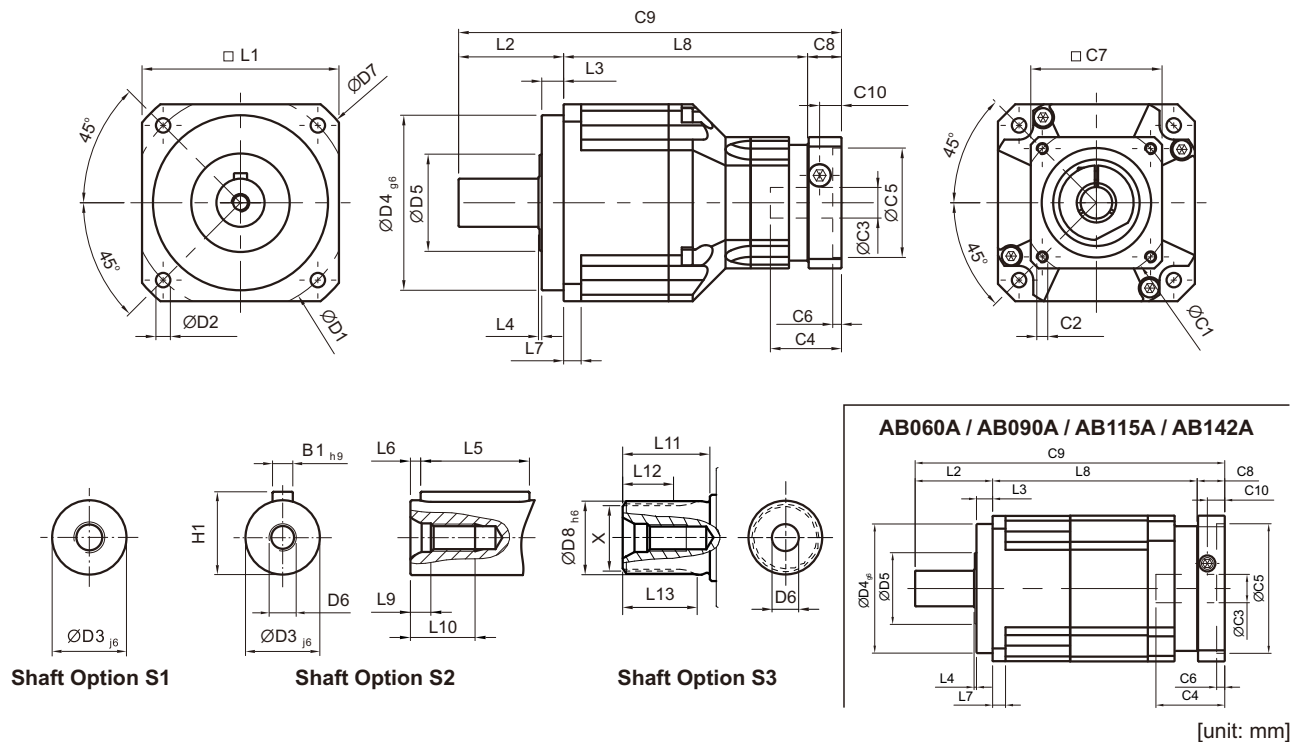
[unit: mm]

Dimension	AB042	AB060	AB090	AB115	AB142	AB180	AB220
D1	50	70	100	130	165	215	250
D2	3.4	5.5	6.6	9	11	13	17
D3 _{j6}	13	16	22	32	40	55	75
D4 _{g6}	35	50	80	110	130	160	180
D5	22	45	65	95	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7	56	80	116	152	185	240	292
D8 _{h6}	-	16	22	32	40	55	75
L1	42	60	90	115	142	180	220
L2	26	37	48	65	97	105	138
L3	5.5	7	10	12	15	20	30
L4	1	1.5	1.5	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	8	10	12	15	20
L8	31	61	78.5	102	119.5	154	163.5
L9	4.5	4.8	7.2	10	12	15	15
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12 ²	≤14 / ≤16 ²	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	86.5	117	143.5	186.5	239	288	364.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 _{h9}	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

2. AB042 ratio 5, 10 offers C3 ≤ 12 option; AB060 ratio 5, 10 offers C3 ≤ 16 option.

Dimensions (2-stage, Ratio $i=12\sim100$) / AB Series



Dimension	AB042	AB060	AB060A	AB090	AB090A	AB115	AB115A	AB142	AB142A	AB180	AB220
D1	50	70		100		130		165		215	250
D2	3.4	5.5		6.6		9		11		13	17
D3 _{j6}	13	16		22		32		40		55	75
D4 _{g6}	35	50		80		110		130		160	180
D5	22	45		65		95		75		95	115
D6	M4 x 0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P		M16 x 2P		M20 x 2.5P	M20 x 2.5P
D7	56	80		116		152		185		240	292
D8 _{h6}	-	16		22		32		40		55	75
L1	42	60		90		115		142		180	220
L2	26	37		48		65		97		105	138
L3	5.5	7		10		12		15		20	30
L4	1	1.5		1.5		2		3		3	3
L5	16	25		32		40		63		70	90
L6	2	2		3		5		5		6	7
L7	4	6		8		10		12		15	20
L8	58.5	72	98	111.5	126.5	143.5	163	176	191	209.5	248
L9	4.5	4.8		7.2		10		12		15	15
L10	10	12.5		19		28		36		42	42
L11	-	26		26		26		40		41.5	52
L12	-	15		15		15		20		21.5	28
L13	-	21		22.5		23		33.5		33.5	45
C1 ³	46	46	70	70	100	100	130	130	165	165	215
C2 ³	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8 x 1.25P	M8 x 1.25P	M10 x 1.5P	M10 x 1.5P	M12 x 1.75P
C3 ³	≤11 / ≤12	≤11 / ≤12	≤14 / ≤16	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤19 / ≤24	≤32	≤32	≤38	≤38	≤48
C4 ³	25	25	34	34	40	40	50	50	60	60	85
C5 ³	30	30	50	50	80	80	110	110	130	130	180
C6 ³	3.5	3.5	8	8	4	4	5	5	6	6	6
C7 ³	42	42	60	60	90	90	115	115	142	142	190
C8 ³	29.5	29.5	19	19	17	17	19.5	19.5	22.5	22.5	29
C9 ³	114	138.5	154	178.5	191.5	225.5	247.5	292.5	310.5	337	415
C10 ³	8.75	8.75	13.5	13.5	10.75	10.75	13	13	15	15	20.75
B1 _{h9}	5	5		6		10		12		16	20
H1	15	18		24.5		35		43		59	79.5
X DIN5480	-	W16 x 0.8 x 30 x 18 x 6m		W22 x 1.25 x 30 x 16 x 6m		W32 x 1.25 x 30 x 24 x 6m		W40 x 2 x 30 x 18 x 6m		W55 x 2 x 30 x 26 x 6m	W70 x 2 x 30 x 34 x 6m

3. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Specifications / ABR Series

Gearbox Performance

Model No.		Stage	Ratio ^A	ABR042	ABR060	ABR060A	ABR090	ABR090A	ABR115	ABR115A	ABR142	ABR142A	ABR180	ABR220
Nominal Output Torque T_{2N}	Nm	1	3	9	36	—	90	—	195	—	342	—	588	1,140
			4	12	48	—	120	—	260	—	520	—	1,040	1,680
			5	15	60	—	150	—	325	—	650	—	1,200	2,000
			6	18	55	—	150	—	310	—	600	—	1,100	1,900
			7	19	50	—	140	—	300	—	550	—	1,100	1,800
			8	17	45	—	120	—	260	—	500	—	1,000	1,600
			9	14	40	—	100	—	230	—	450	—	900	1,500
			10	14	60	—	150	—	325	—	650	—	1,200	2,000
			12	—	55	—	150	—	310	—	600	—	1,100	1,900
			14	—	42	—	140	—	300	—	550	—	1,100	1,800
			16	—	45	—	120	—	260	—	500	—	1,000	1,600
			20	—	40	—	100	—	230	—	450	—	900	1,500
		2	12	12	—	—	—	—	—	—	—	—	—	—
			15	14	—	—	—	—	—	—	—	—	—	—
			16	15	—	—	—	—	—	—	—	—	—	—
			20	14	—	—	—	—	—	—	—	—	—	—
			25	15	60	60	150	150	325	325	650	650	1,200	2,000
			28	19	50	50	140	140	300	300	550	550	1,100	1,800
			30	20	55	55	150	150	310	310	600	600	1,100	1,900
			32	17	45	45	120	120	260	260	500	500	1,000	1,600
			35	19	50	50	140	140	300	300	550	550	1,100	1,800
			40	17	45	45	120	120	260	260	500	500	1,000	1,600
			45	14	40	40	100	100	230	230	450	450	900	1,500
			48	—	—	55	150	150	310	310	600	600	1,100	1,900
			50	14	60	60	100	100	230	230	650	650	1,200	2,000
			60	20	55	55	150	150	310	310	600	600	1,100	1,900
			64	—	—	45	120	120	260	260	500	500	1,000	1,600
			70	19	50	50	140	140	300	300	550	550	1,100	1,800
			80	17	45	45	120	120	260	260	500	500	1,000	1,600
			90	14	40	40	100	100	230	230	450	450	900	1,500
			100	14	40	60	150	150	325	325	650	650	1,200	2,000
			120	—	—	55	150	150	310	310	600	600	1,100	1,900
			140	—	—	50	140	140	300	300	550	550	1,100	1,800
			160	—	—	45	120	120	260	260	550	550	1,000	1,600
			180	—	—	40	100	100	230	230	450	450	900	1,500
			200	—	—	40	100	100	230	230	450	450	900	1,500
Emergency Stop Torque T_{2NOT} ^B	Nm	1,2	3~200	3 times of Nominal Output Torque										
Nominal Input Speed n_{1N}	rpm	1,2	3~200	5,000	5,000	5,000	4,000	4,000	4,000	4,000	3,000	3,000	3,000	2,000
Max. Input Speed n_{1B}	rpm	1,2	3~200	10,000	10,000	10,000	8,000	8,000	8,000	8,000	6,000	6,000	6,000	4,000
Micro Backlash P0	arcmin	1	3~20	—	—	—	≤2	—	≤2	—	≤2	—	≤2	≤2
		2	12~200	—	—	—	≤4	≤4	≤4	≤4	≤4	≤4	≤4	≤4
Reduced Backlash P1	arcmin	1	3~20	≤4	≤4	—	≤4	—	≤4	—	≤4	—	≤4	≤4
		2	12~200	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7	≤7
Standard Backlash P2	arcmin	1	3~20	≤6	≤6	—	≤6	—	≤6	—	≤6	—	≤6	≤6
		2	12~200	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9	≤9
Torsional Rigidity	Nm/arcmin	1,2	3~200	3	7	7	14	14	25	25	50	50	145	225
Max. Radial Load F_{2rB} ^C	N	1,2	3~200	780	1,530	1,530	3,250	3,250	6,700	6,700	9,400	9,400	14,500	50,000
Max. Axial Load F_{2aB} ^C	N	1,2	3~200	390	765	765	1,625	1,625	3,350	3,350	4,700	4,700	7,250	25,000
Service Life ^D	hr	1,2	3~200	20,000										
Efficiency η	%	1	3~20	≥95%										
		2	12~200	≥92%										
Weight	kg	1	3~20	0.9	2.1	—	6.4	—	13	—	24.5	—	51	83
		2	12~200	1.2	1.5	2.7	7.8	7.9	14.2	15.9	27.5	29.6	54	95
Operating Temp	°C	1,2	3~200	-10°C~+90°C										
Lubrication		1,2	3~200	Synthetic lubrication oils										
Degree of Gearbox Protection		1,2	3~200	IP65										
Mounting Position		1,2	3~200	all directions										
Noise ($n_1=3000\text{rpm}$, $i=10$, No load) ^E	dB(A)	1,2	3~200	≤61	≤63	≤65	≤65	≤68	≤68	≤70	≤70	≤72	≤72	≤74

A. Ratio ($i=N_{in}/N_{out}$)B. Max. acceleration torque T_{2B} = 60% of T_{2NOT}

C. Applied to the output shaft center at 100 rpm

D. For continuous operation, the service life time is less than 10,000 hrs

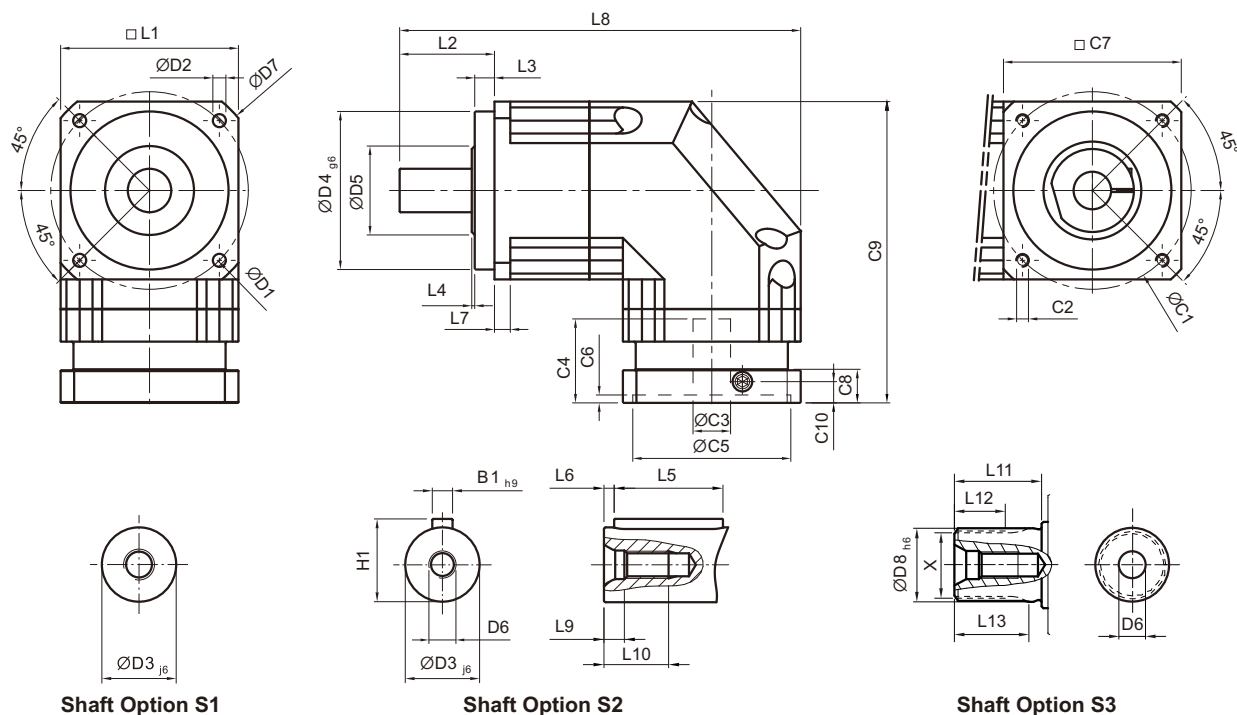
E. These values are measured by gearbox with ratio = 10 (1-stage) or ratio = 100 (2-stage) at 3,000 rpm no loading.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher

Gearbox Inertia

Model No.		Stage	Ratio	ABR042	ABR060	ABR060A	ABR090	ABR090A	ABR115	ABR115A	ABR142	ABR142A	ABR180	ABR220
Mass Moments of Inertia J _i	kg • cm ²	1	3~10	0.09	0.35	—	2.25	—	6.84	—	23.4	—	68.9	135.4
			12~20	—	0.07	—	1.87	—	6.25	—	21.8	—	65.6	119.8
		2	12~20	0.09	—	—	—	—	—	—	—	—	—	—
			25~90	0.09	0.09	0.35	0.35	2.25	2.25	6.84	6.84	23.4	23.4	68.9
			48, 64	—	—	0.07	0.31	1.87	1.87	6.25	6.25	21.8	21.8	65.6
			100~200	—	—	0.07	0.31	1.87	1.87	6.25	6.25	21.8	21.8	65.6

Dimensions (1-stage, Ratio $i=3\sim 20$) / ABR Series

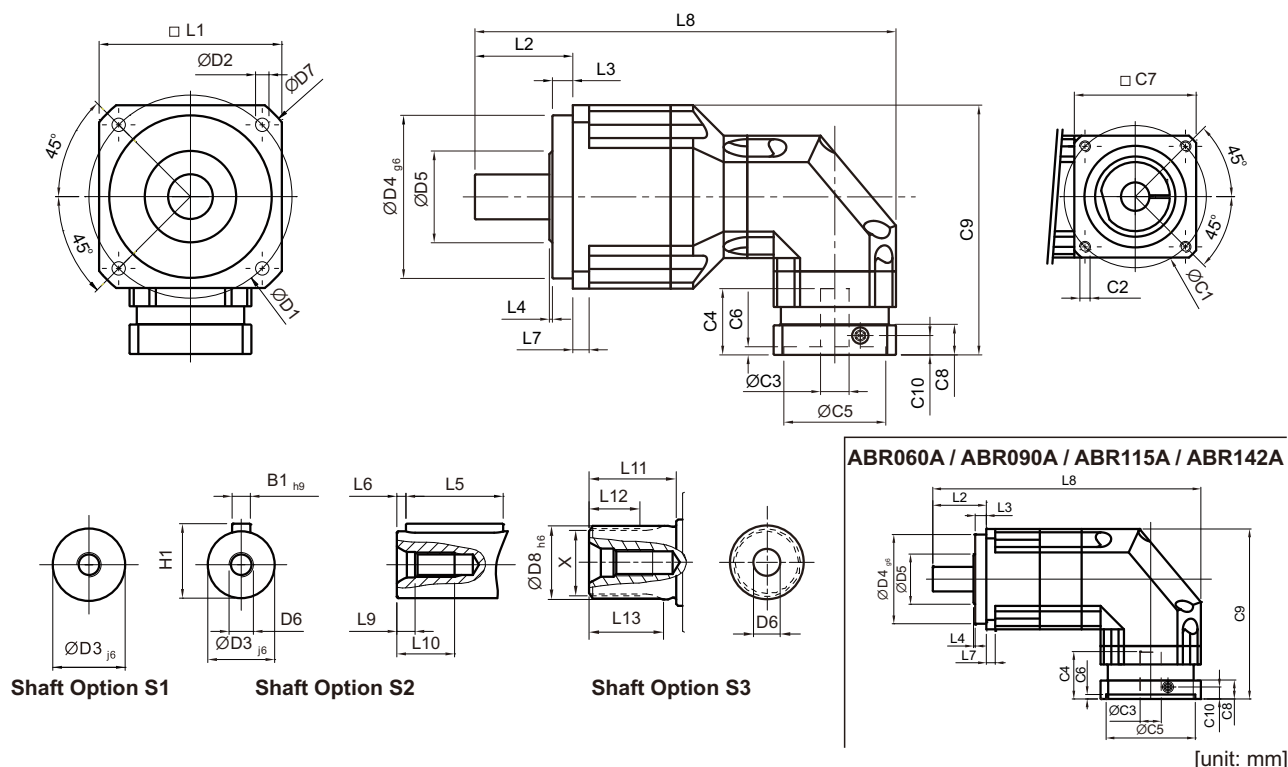


[unit: mm]

Dimension	ABR042	ABR060	ABR090	ABR115	ABR142	ABR180	ABR220
D1	50	70	100	130	165	215	250
D2	3.4	5.5	6.6	9	11	13	17
D3 j6	13	16	22	32	40	55	75
D4 g6	35	50	80	110	130	160	180
D5	22	45	65	95	75	95	115
D6	M4 x 0.7P	M5 x 0.8P	M8 x 1.25P	M12 x 1.75P	M16 x 2P	M20 x 2.5P	M20 x 2.5P
D7	56	80	116	152	185	240	292
D8 h6	-	16	22	32	40	55	75
L1	42	60	90	115	142	180	220
L2	26	37	48	65	97	105	138
L3	5.5	7	10	12	15	20	30
L4	1	1.5	1.5	2	3	3	3
L5	16	25	32	40	63	70	90
L6	2	2	3	5	5	6	7
L7	4	6	8	10	12	15	20
L8	111.5	145	203	259	333	394	484
L9	4.5	4.8	7.2	10	12	15	15
L10	10	12.5	19	28	36	42	42
L11	-	26	26	26	40	41.5	52
L12	-	15	15	15	20	21.5	28
L13	-	21	22.5	23	33.5	33.5	45
C1 ¹	46	70	100	130	165	215	235
C2 ¹	M4 x 0.7P	M5 x 0.8P	M6 x 1P	M8 x 1.25P	M10 x 1.5P	M12 x 1.75P	M12 x 1.75P
C3 ¹	≤11 / ≤12	≤14 / ≤16	≤19 / ≤24	≤32	≤38	≤48	≤55
C4 ¹	25	34	40	50	60	85	116
C5 ¹	30	50	80	110	130	180	200
C6 ¹	3.5	8	4	5	6	6	6
C7 ¹	42	60	90	115	142	190	220
C8 ¹	29.5	19	17	19.5	22.5	29	63
C9 ¹	90.5	111.5	152.5	191.5	235.5	303.5	378.5
C10 ¹	8.75	13.5	10.75	13	15	20.75	53
B1 h9	5	5	6	10	12	16	20
H1	15	18	24.5	35	43	59	79.5
X DIN5480	-	W16x0.8x 30x18x6m	W22x1.25x 30x16x6m	W32x1.25x 30x24x6m	W40x2x 30x18x6m	W55x2x 30x26x6m	W70x2x 30x34x6m

1. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

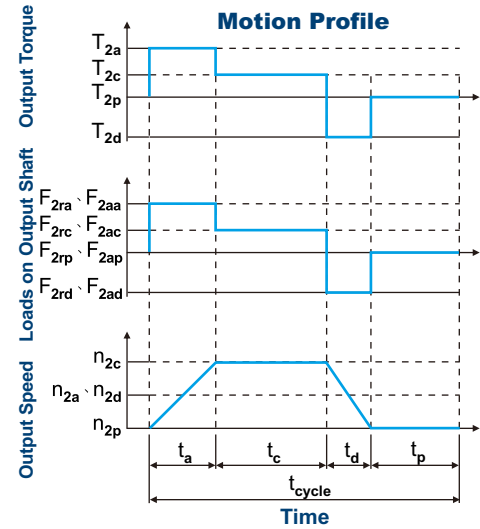
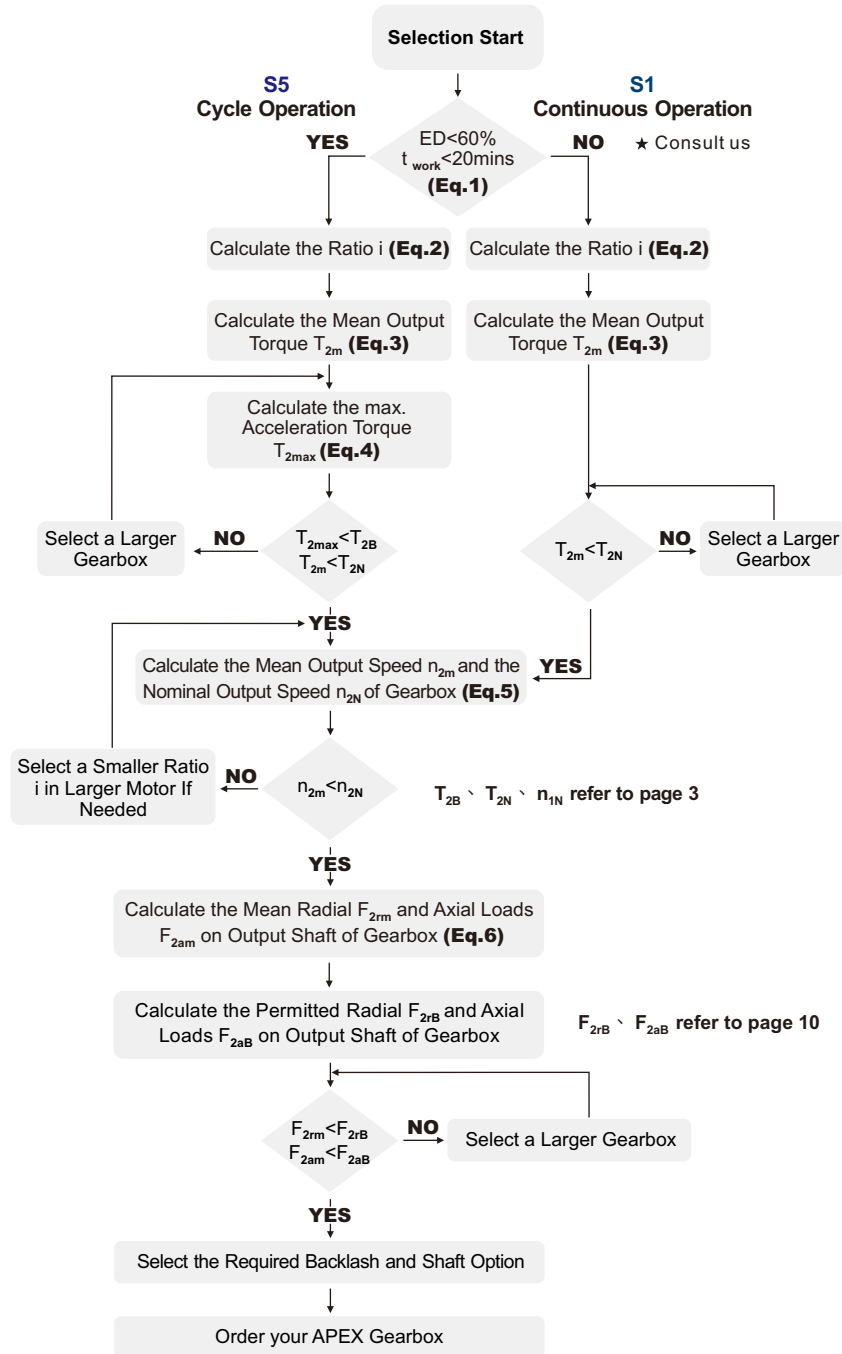
Dimensions (2-stage, Ratio $i = 12 \sim 200$) / ABR Series



Dimension	ABR042	ABR060	ABR060A	ABR090	ABR090A	ABR115	ABR115A	ABR142	ABR142A	ABR180	ABR220
D1	50	70		100		130		165		215	250
D2	3.4	5.5		6.6		9		11		13	17
D3 _{j6}	13	16		22		32		40		55	75
D4 _{g6}	35	50		80		110		130		160	180
D5	22	45		65		95		75		95	115
D6	M4 x 0.7P	M5 x 0.8P		M8 x 1.25P		M12 x 1.75P		M16 x 2P		M20 x 2.5P	M20 x 2.5P
D7	56	80		116		152		185		240	292
D8 _{h6}	-	16		22		32		40		55	75
L1	42	60		90		115		142		180	220
L2	26	37		48		65		97		105	138
L3	5.5	7		10		12		15		20	30
L4	1	1.5		1.5		2		3		3	3
L5	16	25		32		40		63		70	90
L6	2	2		3		5		5		6	7
L7	4	6		8		10		12		15	20
L8	139	163.5	182	206.5	251	285	320	365	404.5	431	521
L9	4.5	4.8		7.2		10		12		15	15
L10	10	12.5		19		28		36		42	42
L11	-	26		26		26		40		41.5	52
L12	-	15		15		15		20		21.5	28
L13	-	21		22.5		23		33.5		33.5	45
C1 ²	46	46	70	70	100	100	130	130	165	165	215
C2 ²	M4 x 0.7P	M4 x 0.7P	M5 x 0.8P	M5 x 0.8P	M6 x 1P	M6 x 1P	M8 x 1.25P	M8 x 1.25P	M10 x 1.5P	M10 x 1.5P	M12 x 1.75P
C3 ²	≤11 / ≤12	≤11 / ≤12	≤14 / ≤16	≤14 / ≤15.875 / ≤16	≤19 / ≤24	≤19 / ≤24	≤32	≤32	≤38	≤38	≤48
C4 ²	25	25	34	34	40	40	50	50	60	60	85
C5 ²	30	30	50	50	80	80	110	110	130	130	180
C6 ²	3.5	3.5	8	8	4	4	5	5	6	6	6
C7 ²	42	42	60	60	90	90	115	115	142	142	190
C8 ²	29.5	29.5	19	19	17	17	19.5	19.5	22.5	22.5	29
C9 ²	90.5	99.5	111.5	126.5	152.5	165	191.5	205	235.5	254.5	323.5
C10 ²	8.75	8.75	13.5	13.5	10.75	10.75	13	13	15	15	20.75
B1 _{h9}	5	5		6		10		12		16	20
H1	15	18		24.5		35		43		59	79.5
X DIN5480	-	W16 x 0.8 x 30 x 18 x 6m		W22 x 1.25 x 30 x 16 x 6m		W32 x 1.25 x 30 x 24 x 6m		W40 x 2 x 30 x 18 x 6m		W55 x 2 x 30 x 26 x 6m	W70 x 2 x 30 x 34 x 6m

2. C1~C10 are motor specific dimensions (metric std shown). Refer to www.apexdyna.com and Design Tool to view your specific motor mounting system.

Selection of the Optimum Gearbox



$$1. ED = \frac{t_a + t_c + t_d}{t_{cycle}} \times 100\%, t_{work} = t_a + t_c + t_d$$

Index : a. Acceleration, c. Constant, d. Deceleration, p. Pause (Eq.1)

$$2. i \cong \frac{n_m}{n_{work}}$$

n_m Output Speed of the Motor
 n_{work} Working Speed (Eq.2)

$$3. T_{2m} = \sqrt[3]{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.3)

$$4. T_{2max} = T_{mB} \times i \times k_s \times \eta$$

where K_s is

K_s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2,000 ~ 3,000
1.8	3,000 ~ 5,000

T_{mB} Max. Output Torque of the Motor

η Efficiency of the Gearbox (Eq.4)

$$5. n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

$$n_{2N} = \frac{n_{1N}}{i}$$

(Eq.5)

$$6. F_{2rm} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2ra}^3 + n_{2c} \times t_c \times F_{2rc}^3 + n_{2d} \times t_d \times F_{2rd}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

$$F_{2am} = \sqrt[3]{\frac{n_{2a} \times t_a \times F_{2aa}^3 + n_{2c} \times t_c \times F_{2ac}^3 + n_{2d} \times t_d \times F_{2ad}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$

(Eq.6)

Recommended (for S5 Cycle Operation)

The general design is given for

$$\frac{J_L}{i^2} \leq 4 \times J_m$$

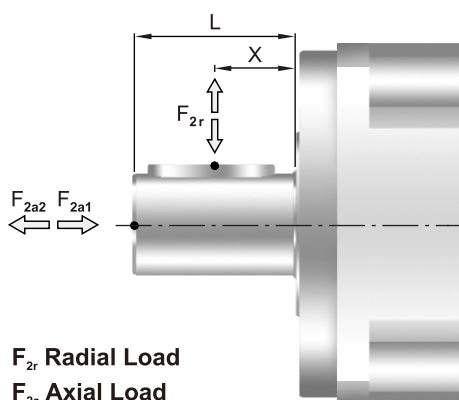
The optimal design is given for

$$\frac{J_L}{i^2} \cong J_m$$

J_L Load Inertia

J_m Motor Inertia

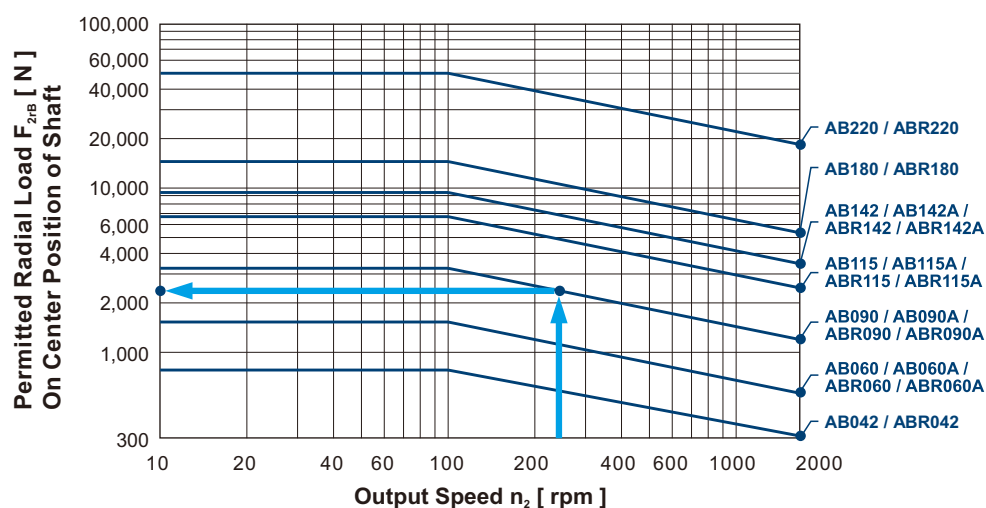
Permitted Radial and Axial Loads



The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings.

APEX use the extension straddle oversized ball bearing design.

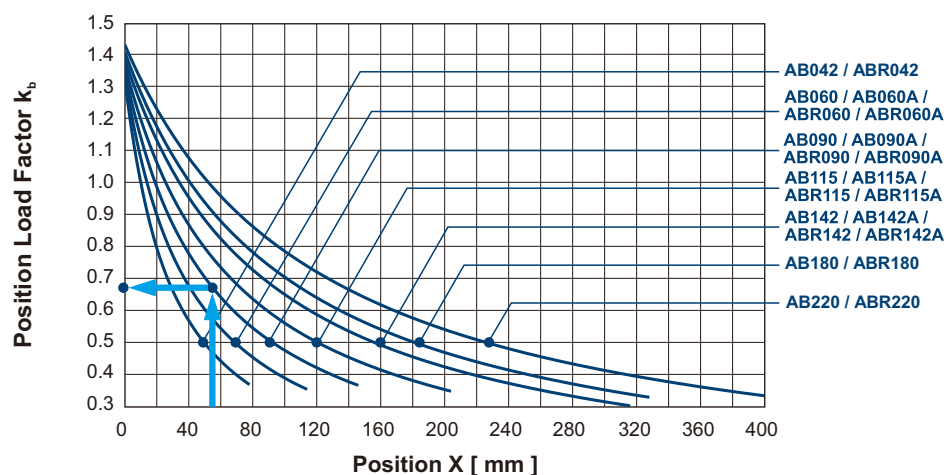
It can take heavy load from both axes.



If radial force F_{2r} exert on the center of the output shaft $X=1/2 \times L$.

Under various operating condition the lifetime is over 20,000* hours.

The permitted radial load is given on left diagram.



If radial force F_{2r} not exert on the center of the output shaft $X < 1/2 \times L$ or $X > 1/2 \times L$

The permitted radial and axial load can be calculated by the position load factor K_b on the left diagram.

* S1 service life 10,000 hrs



APEX TAIWAN NORTH
ANDTEK AUTOMATION CO.,LTD
 TEL +886-02-82262655
 13F-5, No.2, Jian 8th Rd., Jhonghe Dist., New
 Taipei City 235, TAIWAN
sales@andtek.com.tw
www.apexdyna.com



APEX TAIWAN CENTRAL
ANDTEK AUTOMATION CO.,LTD
 TEL +886-04-23594286
 9F-6, No.925, Sec.4, Taiwan Blvd., Xitun Dist.
 Taichung City 407 TAIWAN
sales@andtek.com.tw
www.apexdyna.com



APEX TAIWAN SOUTH
MEN JENN ELECTRIC CO., LTD.
 TEL +886-06-2337332 ~ 6
 No.774, Zhonghua Rd., Yongkang Dist., Tainan
 City 710, TAIWAN
menjenn@ms24.hinet.net
www.apexdyna.com



APEX DYNAMICS INC. SHANGHAI
 TEL +86-21-69220577
 No.128 ZHUYING Road QINGPU Industry Area,
 Shanghai, CHINA
sales@apexdyna.cn
www.apexdyna.cn



APEX DYNAMICS SHENZHEN, LTD.
 TEL +86-755-84516325
 No. 1102A of D area , CFG mansion ,Bao Yuan
 Road , Bao' an District , Shenzhen ,CHINA.
sales@szapexdyna.com
www.szapexdyna.com



APEX DYNAMICS BEIJING, LTD.
 TEL +86-10-69570691
 NO.1,YaoPingRoad,SongZhuang Town, Tongzhou
 istrict, Beijing, CHINA.
bjapexdyna@163.com
www.bjapex.cn



CHONGQING APEX DYNAMICS CO., LTD.
 TEL +86-23-67686860
 406, Building 5, No.68,Jinyu Avenue, Beibu New
 Area, Chongqing, CHINA
sales@cqaapexdyna.com
www.apexdyna.com



APEX (XIAMEN) DYNAMICS TECHNOLOGY CO., LTD.
 TEL +86-0592-720-5279
 Unit B-3,1F.,No.129,Jingquan Road, Jimei District,
 Xiamen, Fujian, CHINA
sales@xmapexdyna.com
www.xmapexdyna.com



APEX DYNAMICS USA, INC.
 TEL +1-631-2449040
 885 Marconi Avenue Ronkonkoma, NY 11779
 U.S.A.
sales@apexdynamicsusa.com
www.apexdynamicsusa.com



APEX DYNAMICS KOREA
 TEL +82-31-8179992
 1246-32, Seongsuk-dong, Ilsandong-gu, Goyang-city,
 Gyeonggi-Do, KOREA (R.O.K) 410-570
sales@apexdynakorea.co.kr
www.apexdynakorea.co.kr



APEX DYNAMICS JAPAN
 TEL +81-092-4511202
 1-13-3, Sannou, Hakata-ku, Fukuoka-Shi 812-0015,
 JAPAN
sales@apexdyna.jp
www.apexdyna.jp



APEX DYNAMICS SINGAPORE PTE LTD
 TEL +65-62-626228
 3 South Buona Vista Road, #05-15 & #06-15.
 SINGAPORE 118136
sales@apexdyna.com.sg
www.apexdyna.com.sg



APEX DYNAMICS (THAILAND) CO., LTD.
 TEL +66-2-3266233
 73 Soi Ladkrabang 30, Kadkrabang Rd.,Bangkok
 10520, THAILAND
sales@apexdyna.co.th
www.apexdyna.co.th



APEX DYNAMICS BV
 TEL +31-492-509995
 Churchillaan 101 5705 BK Helmond, NETHERLANDS
sales@apexdyna.nl
www.apexdyna.nl
www.apexdyna.be



APEX DYNAMICS
POLSKA SP. Z O.O.
 TEL +48-12-6304728
 Krakowska 50, 32-083 Balice, POLAND
sales@apexdyna.pl
www.apexdyna.pl



APEX DYNAMICS SPAIN, S.L.
 TEL +34-93-6562990
 Poligono Industrial Molí dels Frares, Calle C nº
 12,08620 - Sant Vicenç dels Horts, Barcelona, SPAIN
apexdyna@apexdyna.es
www.apexdyna.es



APEX DYNAMICS IRAN.
 TEL +98-21-66593517
 APT#6, 3rd Flr, No.5, 3rd Kowsar St., Sattarkhan
 Ave., Tehran, IRAN
alahyari@farasysco.com
www.apexdyna.ir



APEKS REDUKTOR VE DISLI SAN. TIC. LTD. STI.
 TEL +90-232-4589960
 10042 Sok.No:10 AOSB Çiğli-İzmir, TURKEY
sales@apexdyna.com.tr
www.apexdyna.com.tr



APEX DYNAMICS AUSTRALIA PTY LTD.
 TEL +613-95-852739
 36 Taunton Drive, Cheltenham, Victoria 3192
 AUSTRALIA.
sales@apexdyna.com.au
www.apexdyna.com.au



APEX DYNAMICS (I) JV
 TEL +91-80-55345541
 GAT NO. 279, KHED SHIVAPUR BAUG, TALUKA
 HAVELI PUNE- 412205 INDIA.
sales@apexdyna.co.in
www.apexdyna.co.in



APEX DYNAMICS FRANCE SAS
 TEL +33-160-135097
 11 - Burospace F - 91570 -
 Bièvres, FRANCE
info@apexdyna.fr
www.apexdyna.fr



APEX DYNAMICS SWEDEN AB
 TEL +46-75-242444
 Fredrikbergsgatan 2 SE-573 92 Tranås, SWEDEN
sales@apexdyna.se
www.apexdyna.se



PT.APEX DYNAMICS INDONESIA
 TEL +62 21 2928 3681
 Rukan Aralia Blok HY43 no.11, Harapan Indah II,
 Bekasi - Jawa Barat, INDONESIA 17214
sales@apexdyna.co.id
www.apexdyna.co.id



APEX DYNAMICS GERMANY GMBH
 TEL +49-7181-9329955
 Spanninger Str. 9, 73650 Winterbach, GERMANY
Langer@apexdynamics.de
www.apexdynamics.de



APEX DYNAMICS CZECH S.R.O.
 TEL +420-577-663877
 tř. Tomáše Bati 1851 765 02 Otrokovice ČESKÁ
 REPUBLIKA
info@apexdynaczech.cz
www.apexdynaczech.cz



APEX DYNAMICS РОССИЯ
 TEL +7-495-2255452
 +7-495-6462422
 г.Москва, ул. Южнопортовая, дом 7, строение
 “С”, 3-й этаж
info@apexdynarussia.ru
www.apexdynarussia.ru



APEX DYNAMICS UK LIMITED
 TEL +44-1827-253340
 2 Centurion Way, Centurion Park, Tamworth
 Staffs, B77 5PN, UK
sales@apexdynamicsuk.com
www.apexdynamicsuk.com



APEX DYNAMICS SWITZERLAND AG
 TEL +41-55-4517020 Talstrasse 24, CH-8852
 Altendorf, SWITZERLAND
info@apexdyna.ch
www.apexdyna.ch



APEX DYNAMICS MOTION SDN BHD
 TEL +60 7237 1055
 No.1, Jalan Perniagaan Setia 3, Taman
 Perniagaan Setia, 81100 Johor Bahru, Johor,
 MALAYSIA (Setia Business Park 2 @ Iskandar
 Malaysia)
sales@apexdyna.com.sg
www.apexdyna.com.sg



APEX DYNAMICS BRAZIL
 TEL +55-47-30298700
 Rua Senador Petrônio Portela, 47 - Bloco 5, Zona
 Industrial Norte - CEP 89218-575 - Joinville (SC)
luacan@neoyama.com.br
adriano.duarte@neoyama.com.br
www.neoyama.com.br



APEX DYNAMICS ITALY
 TEL +39 02.36634521
 VIA E. DE AMICIS, 2 – 20091 BRESSO (MI)
info@apexdynamics.it
www.apexdynamics.it



APEX DYNAMICS, INC.

No. 10, Keyuan 3rd Rd., Situn District, Taichung City 40763, Taiwan (R.O.C.)
 Tel:886-4-24650219 | Fax:886-4-24650118
sales@apexdyna.com | <http://www.apexdyna.com>

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